



Observatoire
de Paris



CARIOQA

Quantum accelerometry for space geodesy

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Workshop Application of Time-Frequency technologies
to defense and space science
Rennes, 09/10/2025



Outline

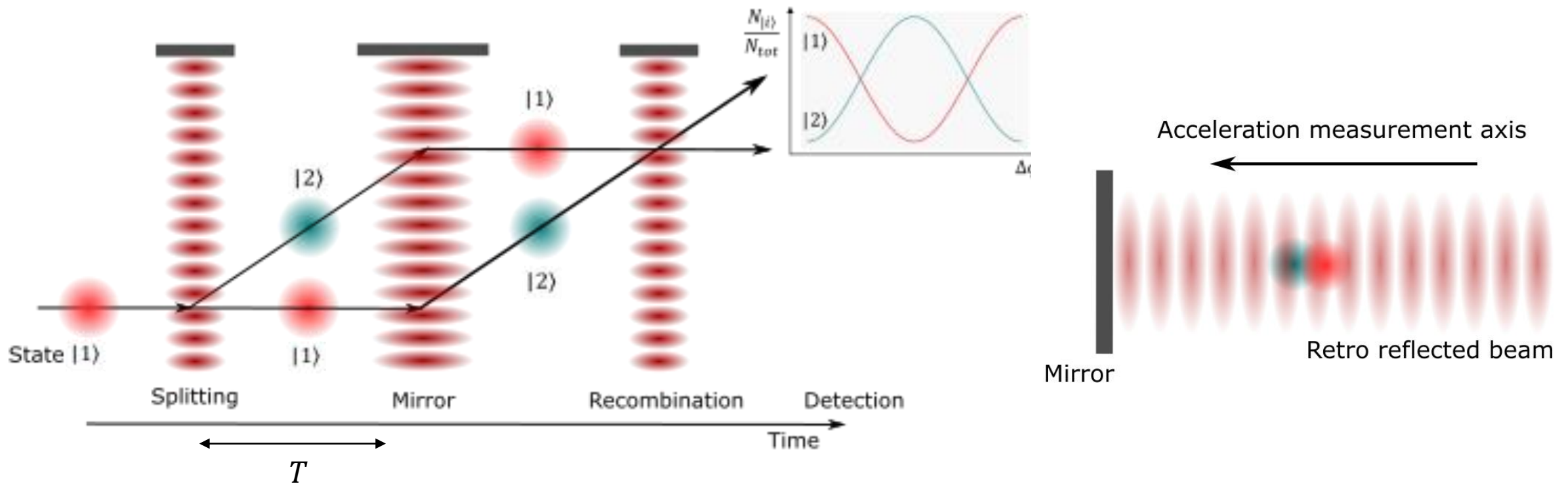
- Quantum accelerometry on the ground and in space
- The CARIOQA project
- Challenges related to the space environment
- An instrument simulator

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Principle of a cold atom accelerometer

A cloud of cold (1 μ K) or ultracold (10 nK) atoms, free falling or trapped.



For a free falling accelerometer : $\Delta\Phi = k_{eff}aT^2$

Cycling measurement with $T_c = 2T + T_d$

$T_d \sim 0.1 - 2$ s dead time for preparation and detection

Maturity of the technology

Inertial sensing technologies based on atom interferometry : 30 years of development



SYRTE
gravimeter



KSS32 relative Marine Gravimeter
(Bodenseewerk)

Cold Atom Gravimeter
(Onera)

A mature technology: industrial transfer from the lab to commercial products

Many applications :

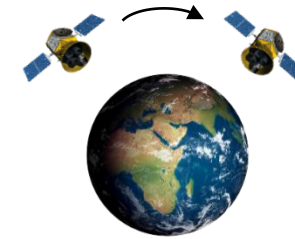
- Gravimetry
- Gradiometry
- Inertial sensing and navigation
- Fundamental physics



eXail
gravimeter

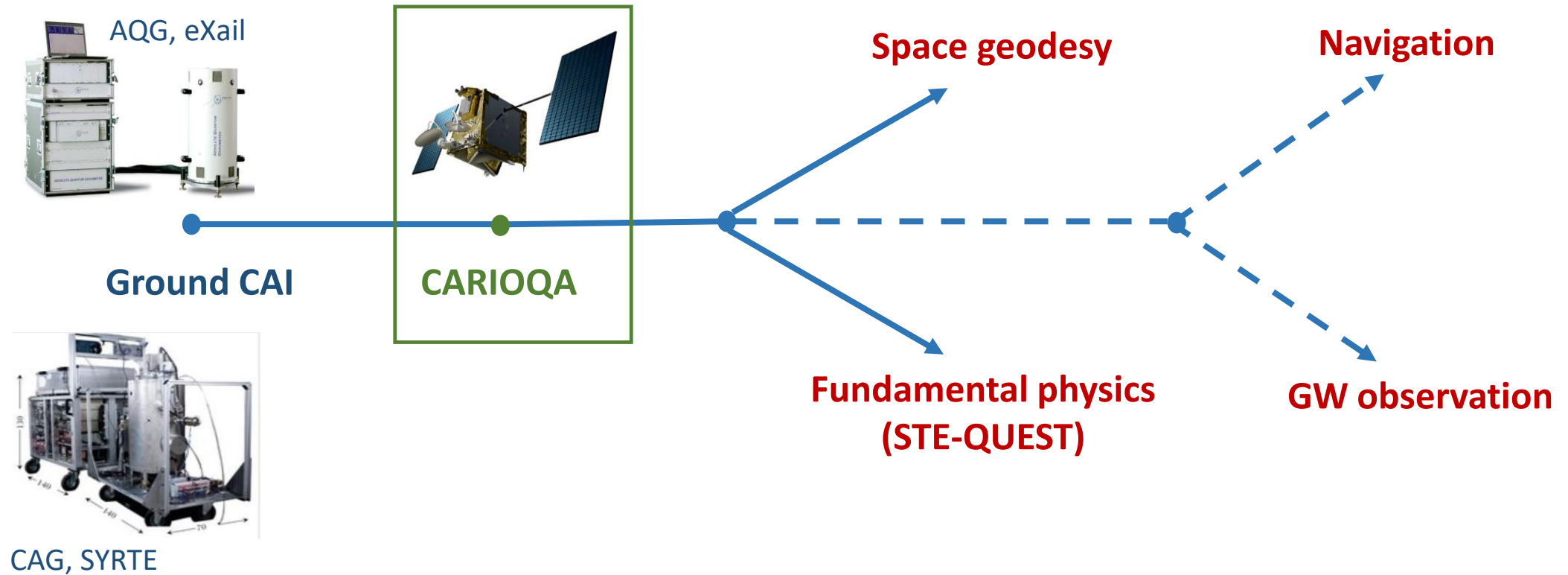
Adapting CAI to space

- Microgravity :
 - **Larger interrogation time** (sensitivity scales in T^2).
 - On ground : typical time 500 ms.
 - **In space, $T = 10$ s possible : gain of 2-3 orders of magnitude.**
 - New limiting factor : **temperature**. Expansion for a thermal cloud : 10 cm after 10 s.
- Navigation (Altitude 300 km) :
 - Acceleration is not constant.
 - Sensitivity to **residual rotations**.
 - **Nadir pointing** : constant rotation at 1.3 mrad/s.
- Limited size and power budget



Perspectives

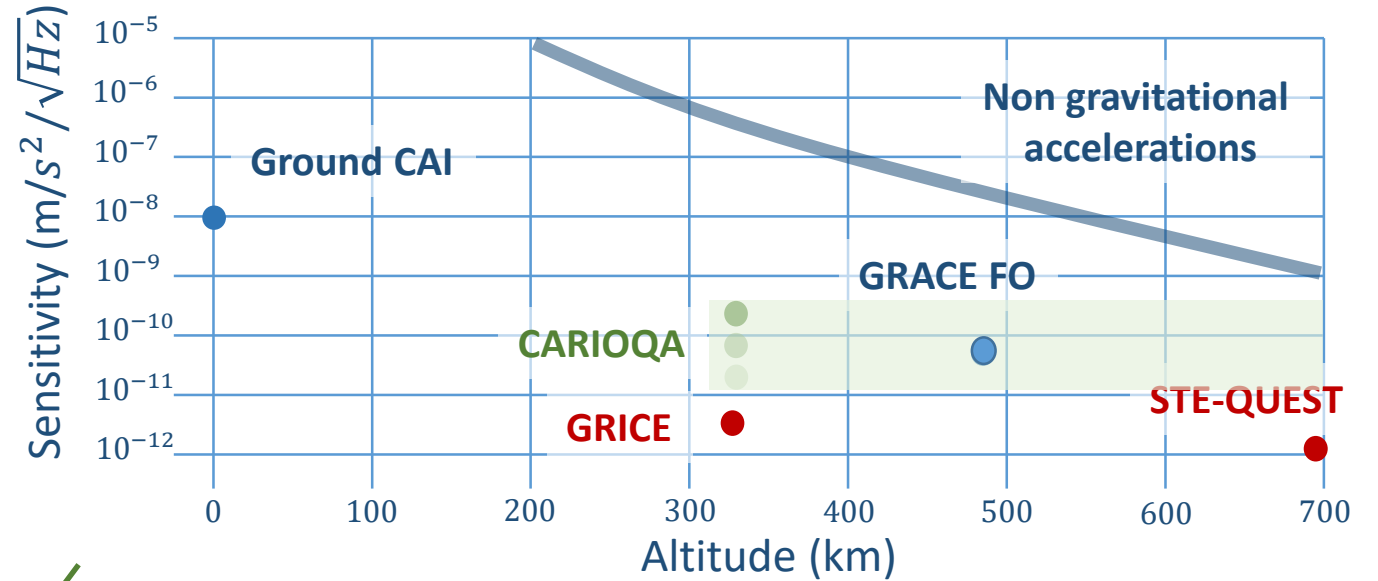
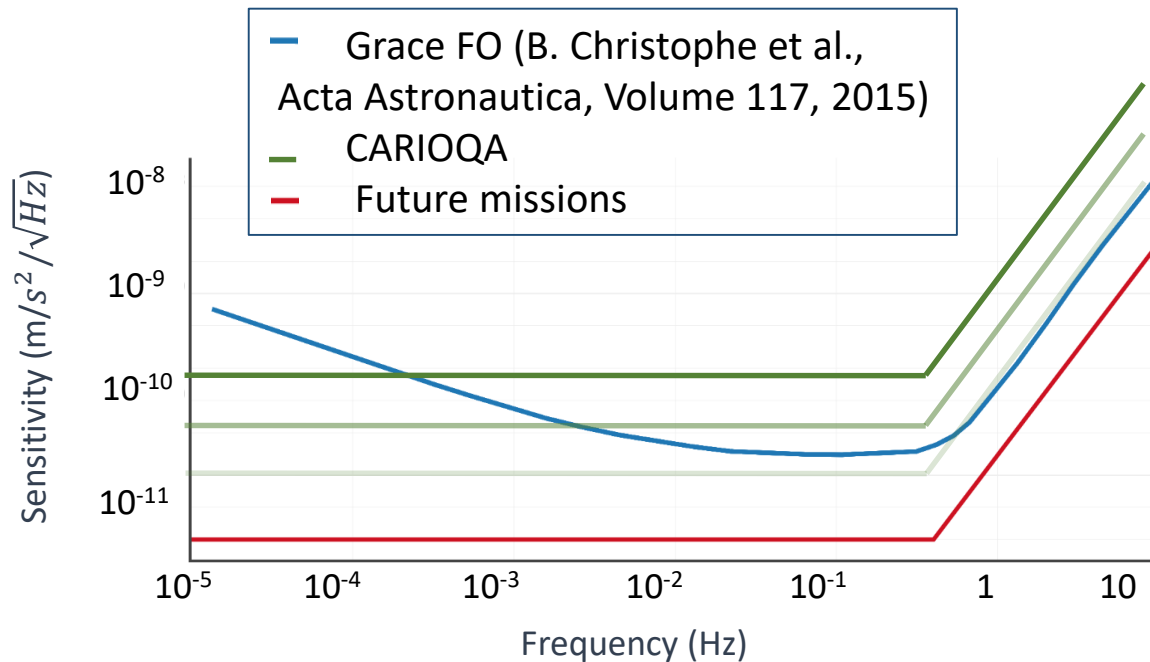
Towards Cold Atom Interferometer (CAI) based space missions



Expected level of performances

To be competitive,
CAI should demonstrate
in orbit performances
 $< 10^{-11} \text{ m/s}^2 / \sqrt{\text{Hz}}$

3 orders of magnitude improvement!

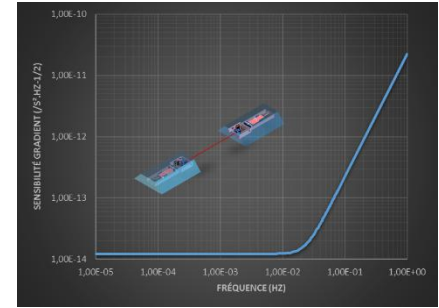


Key advantage of CAI :
Long term stability (absolute measurement)

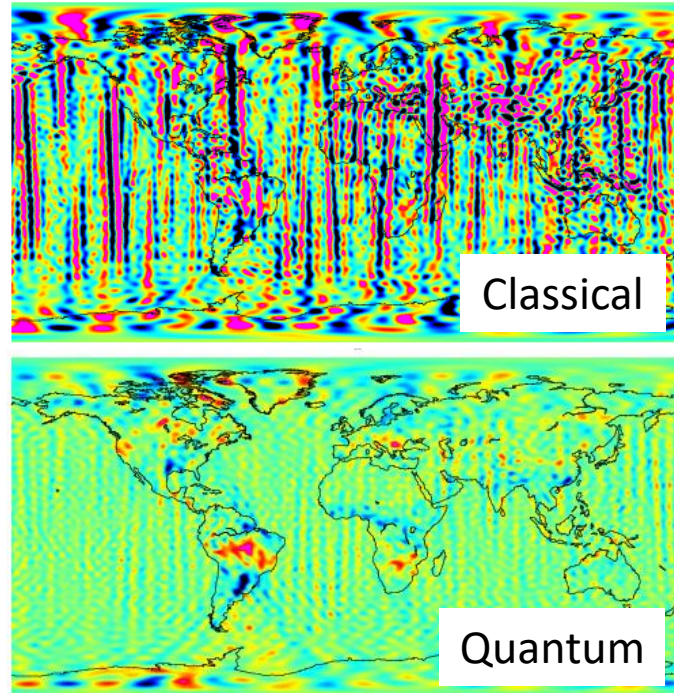
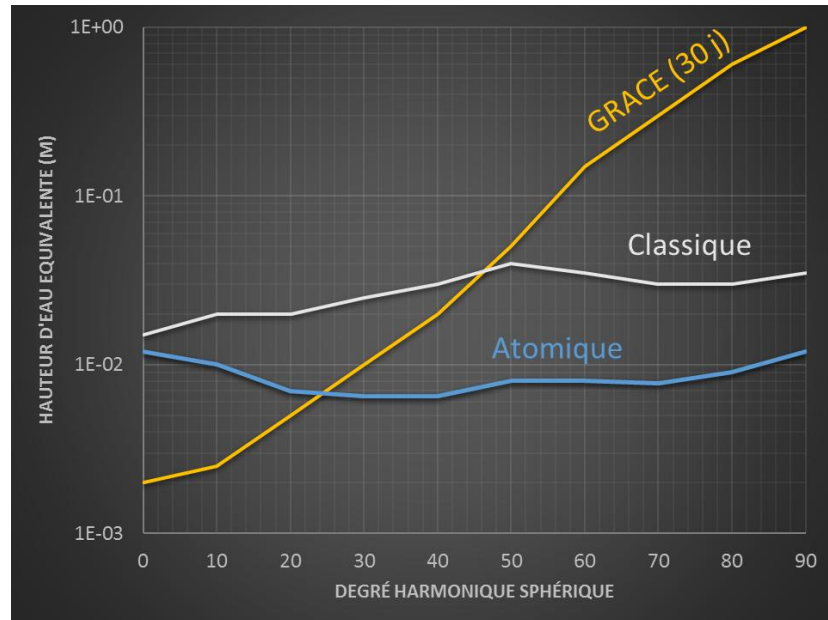
GRICE: a CNES Phase 0 (2016-2018)

Mission configuration GRACE-like (L=100 km)

Instrument performances (LRI 40 nm/Hz^{1/2} and QA 6 10⁻¹⁰ m/s²/Hz^{1/2})



Comparison between restitution errors with different accelerometers applying the same data processing
Classical accelerometer has a « typical » drift + no empirical parameters to reduce the impact of the drift

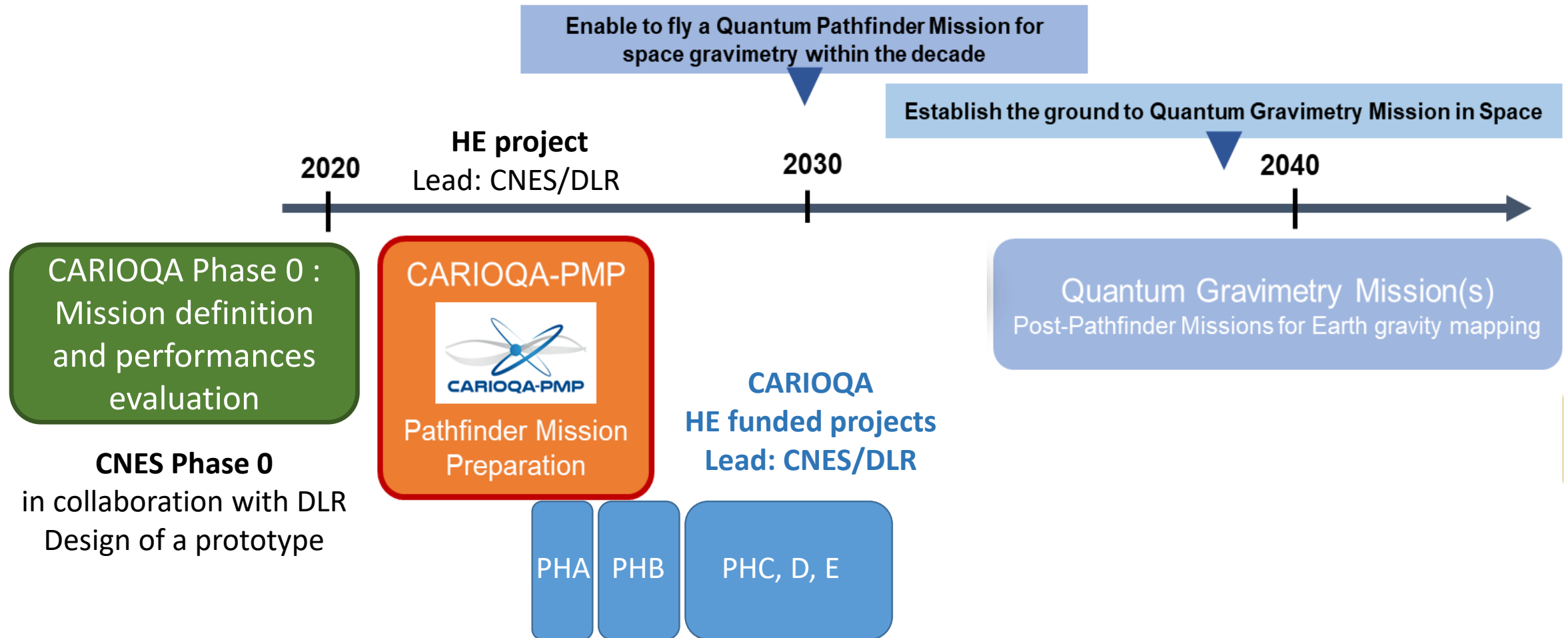


- Less stripes for the quantum sensor
- No (less) need for data reduction that modify the gravity field

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The CARIOQA project



<https://carioqa-quantumpathfinder.eu/>

Mission objectives

Primary objectives:

- Demonstrate the acceleration measurement capability
- Assess the level of noise
- Evaluate the accuracy of the accelerometer
- Manage rotations

Secondary objectives:

- Gravity field recovery (HL-SST)
- Measurement of the thermosphere density



Technological
demonstrator



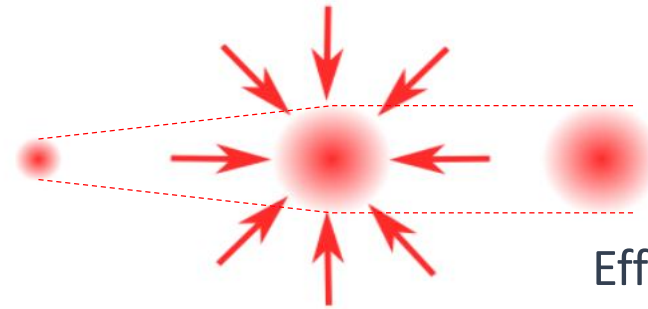
**Funded by
the European Union**

Space heritage

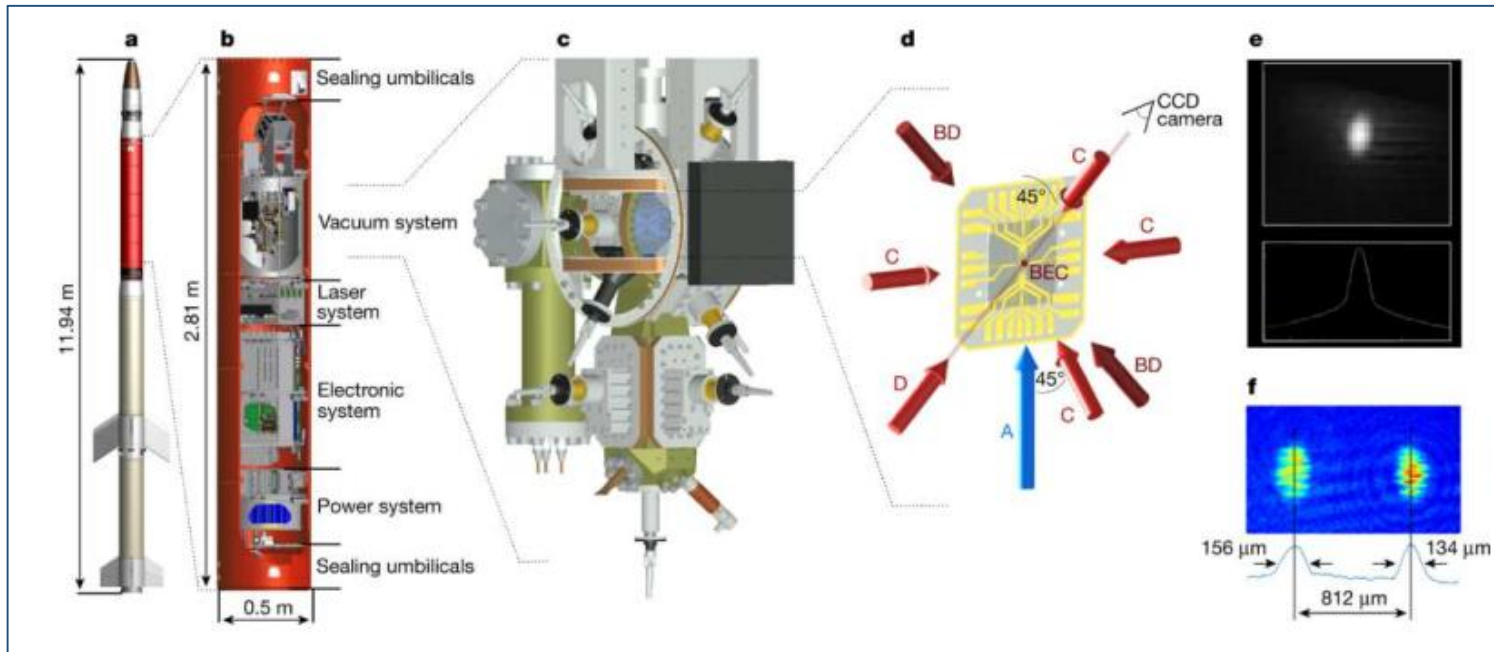
PHARAO: cold atoms in space

MAIUS: ultracold atoms in space

- Laser and evaporative cooling on an atom chip.
- delta-kick collimation.



Effective temperature
< 100 pK

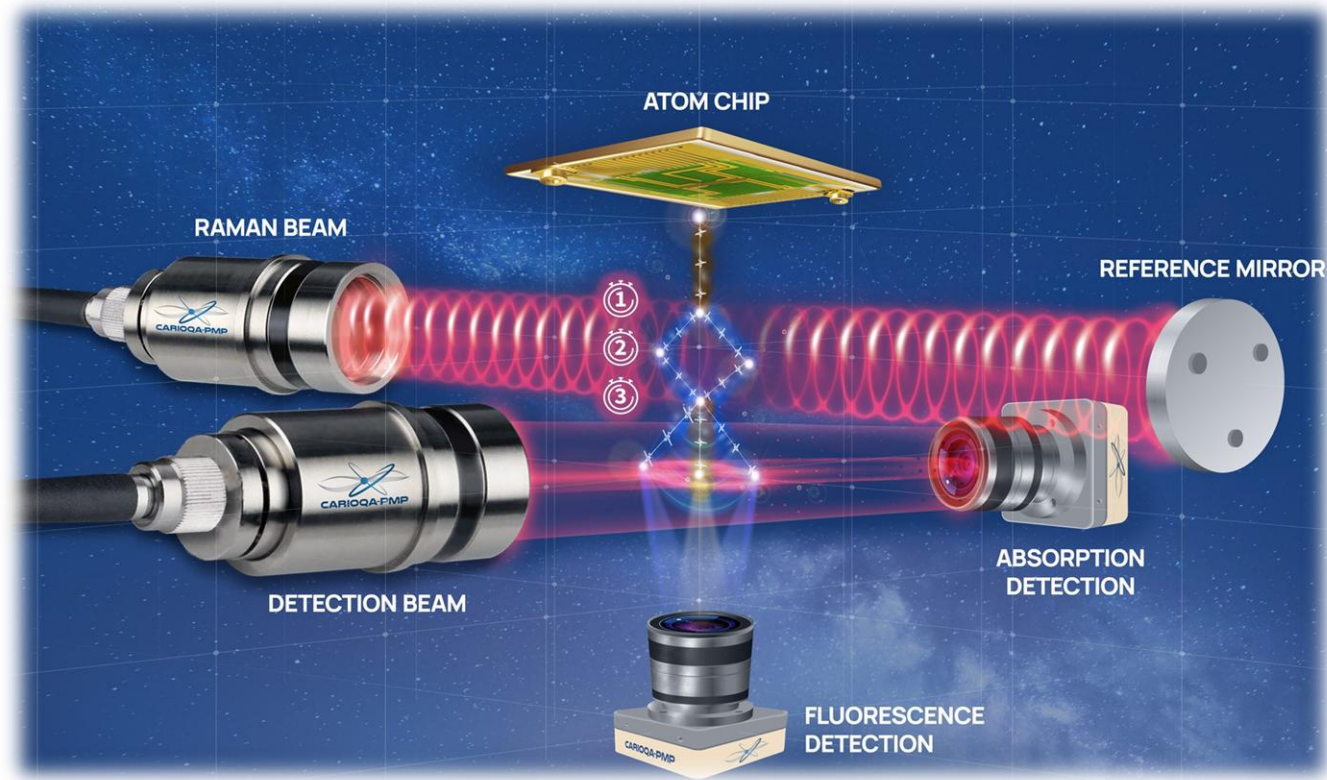


Becker, D., Lachmann, M.D., Seidel, S.T. *et al.* Space-borne Bose–Einstein condensation for precision interferometry. *Nature* **562**, 391–395 (2018)

CARIOQA-PMP

Realisation of an engineering model by an industrial consortium

Airbus, exail, Leonardo for space qualified hardware (PP, laser system and RF source) + Teletel for EGSE



Integration and tests in CNES facilities

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Coping with rotations

Phase of the rotating interferometer:

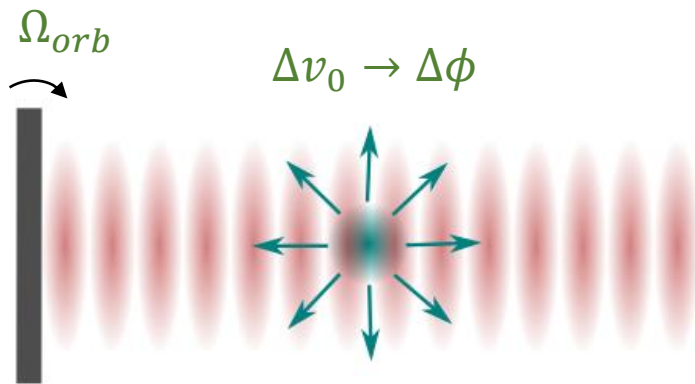
$$\phi = k_{eff} T^2 [a_x - 2v_{0z}\Omega_y + x_0 \Omega_y^2] + O[\Omega T]^3$$

Non inertial acceleration

Coriolis

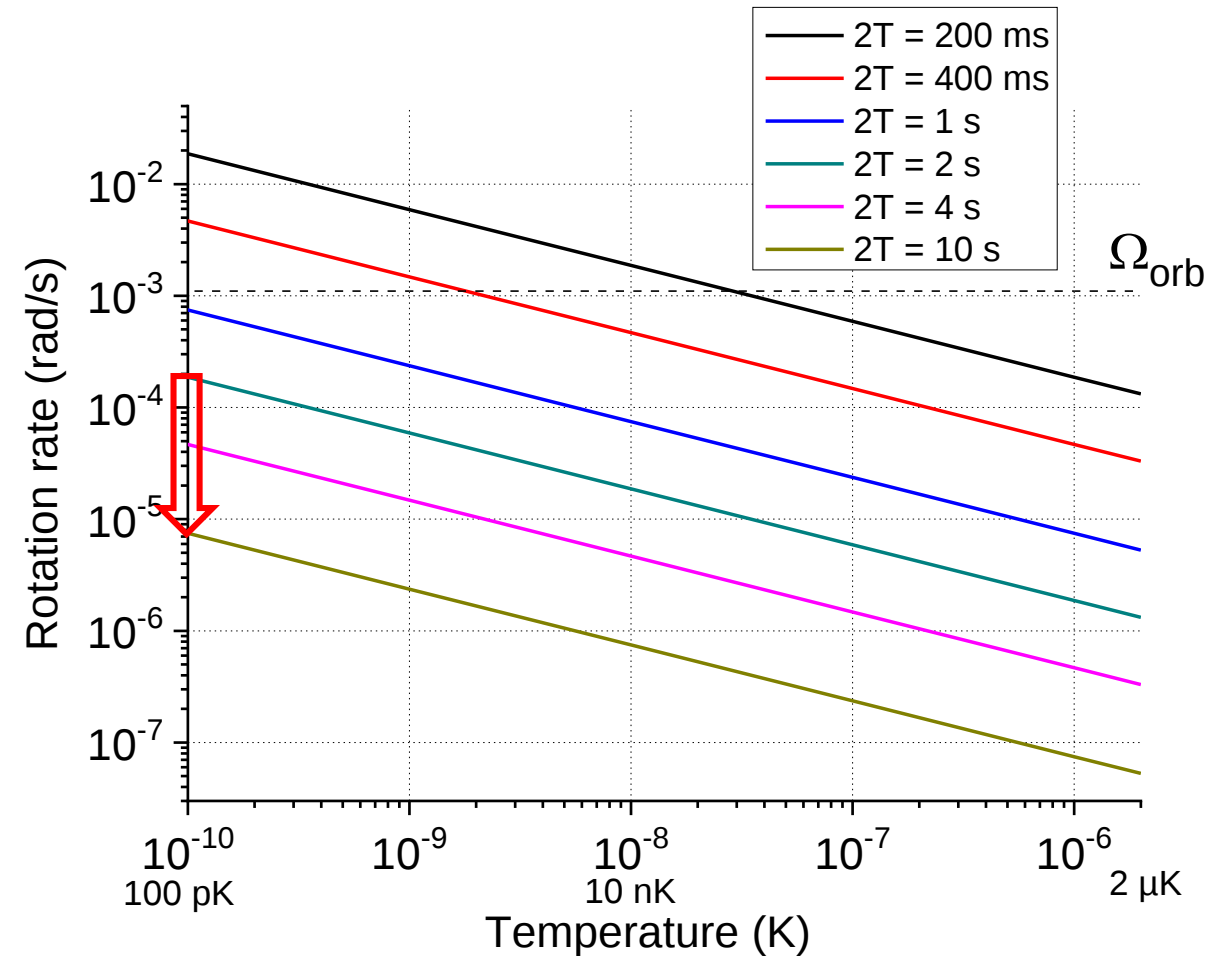
centrifugal

Velocity dispersion induces a **phase inhomogeneity**



This leads to a **loss of contrast**

$$C = e^{-\frac{\sigma_\phi^2}{2}} = e^{-2(k\sigma_v\Omega T^2)^2}$$



Max residual rotation to keep contrast above 50%

Even at very low temperature,
Nadir rotation has to be compensated

Compensation of nadir rotation

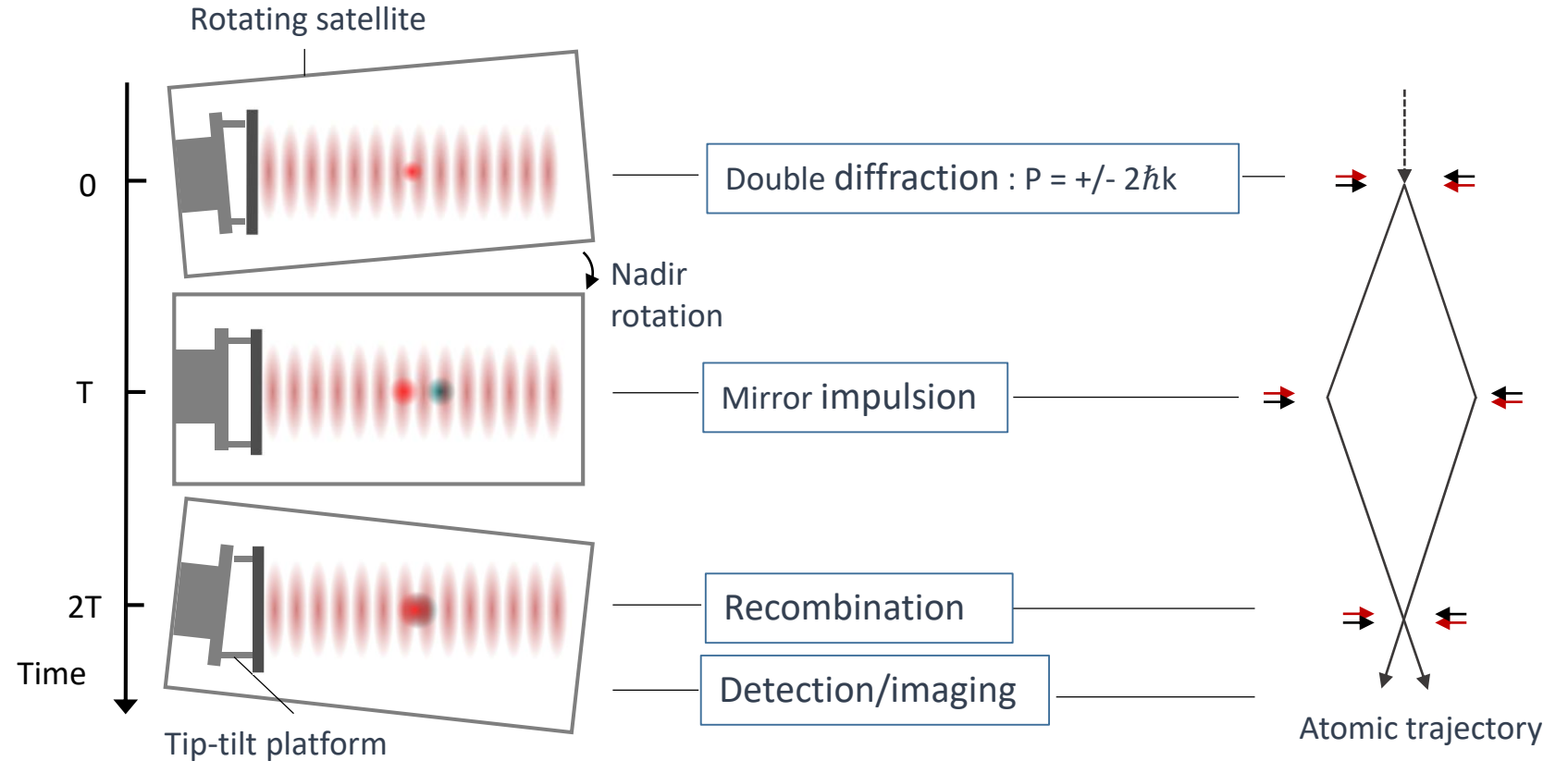
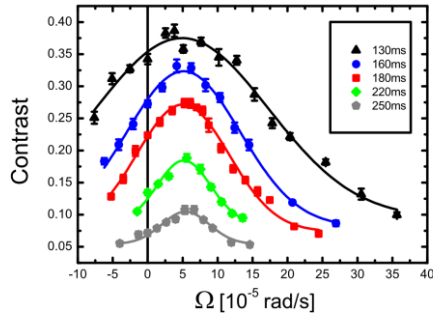
Counter-rotating the mirror:

$$\Omega_m = -\Omega_y \approx 1 \text{ mrad/s.}$$

Technical solution:

piezo tip-tilt

Demonstrated on the ground
(Earth rotation compensation)



Rotation of the mirror at angular velocity Ω_m and rotation of the incoming laser Ω_I

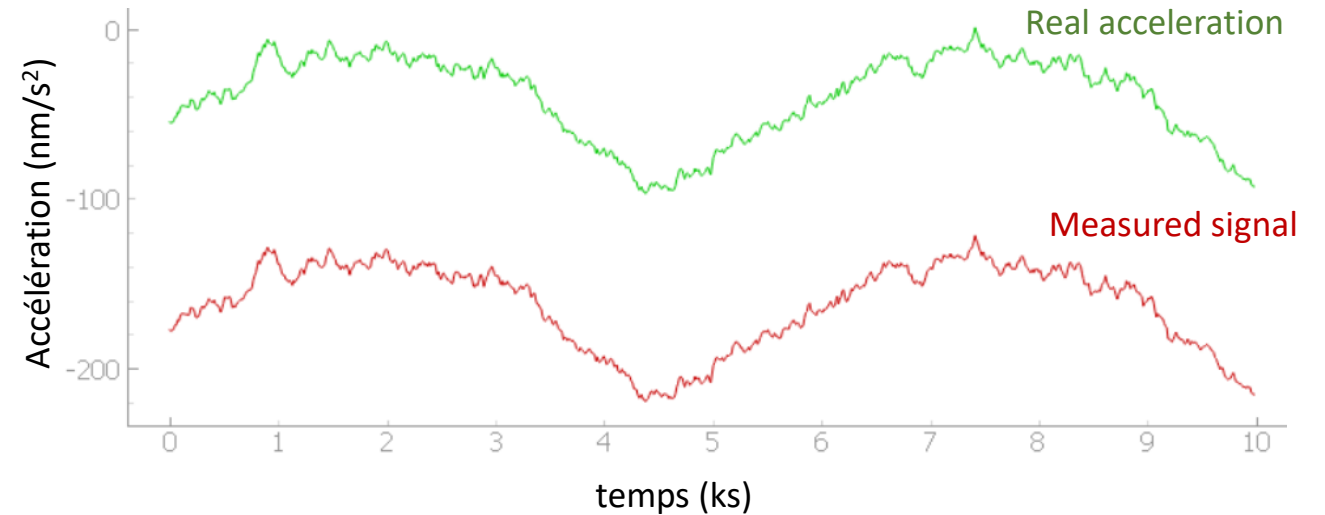
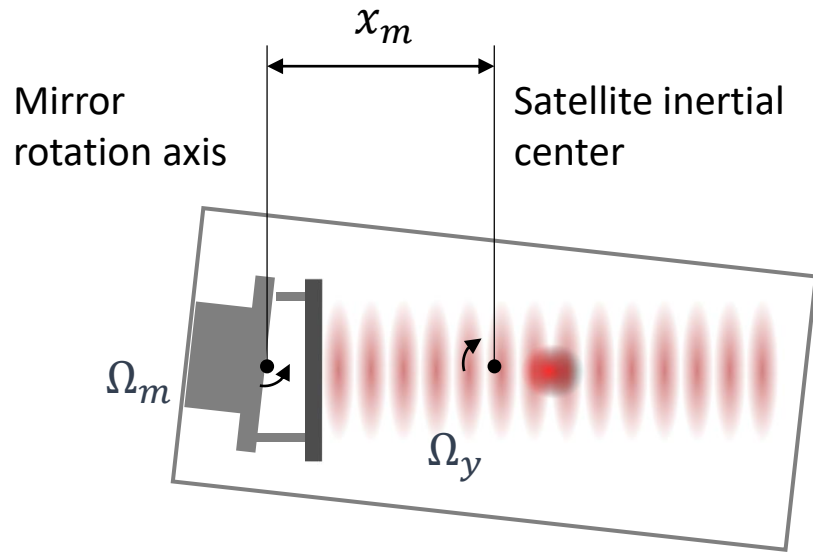
$$\phi = k_{eff} T^2 [a_x + 2v_{0z}(\Omega_y + \Omega_m) - x_0 \Omega_y^2 + (x_0 - x_m)(\Omega_m^2 + (\Omega_m - \Omega_I)^2) + O[\Omega T]^3]$$

Compensation bias

Assuming that the incoming laser beam is co-rotated $\Omega_m = \Omega_I$:

$$\phi = k_{eff} T^2 [a_x + 2v_{0z}(\Omega_y + \Omega_m) - x_0 (\Omega_y^2 - \Omega_m^2) - \boxed{x_m \Omega_m^2}] + O[\Omega T]^3$$

For $\Omega_m = -\Omega_y$, acceleration bias : $x_m \Omega_m^2$



Acceleration signal for $x_m = 10$ cm

Importance of the rotation center's position for accuracy : for 10^{-10} m/s^2 , x_m must be known better than 0.1 mm.

Non-linearity of the response

Measurand : the transition probability : $P = A + \frac{C}{2} \cos \varphi = A + \frac{C}{2} \cos(kaT^2)$

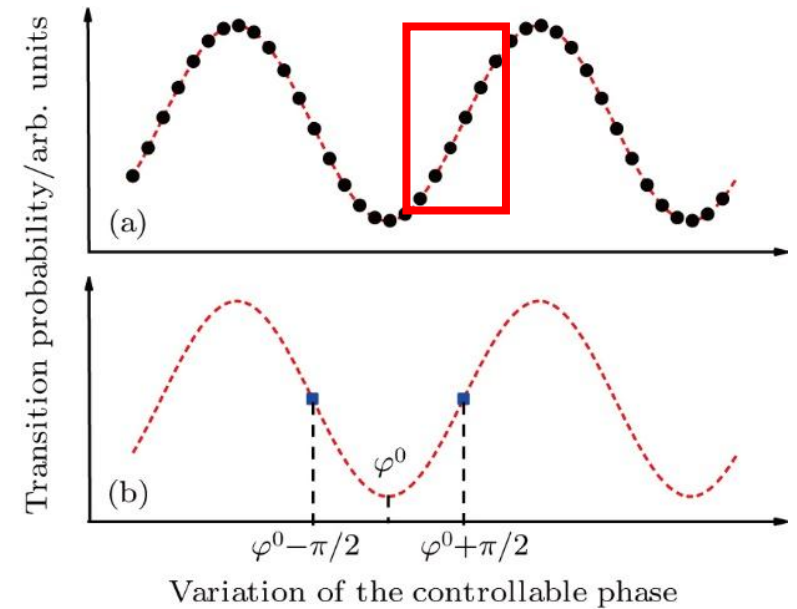
=> Non-linear response + phase ambiguity

Ideally, operation at mid fringe
and for acceleration fluctuations such that $k\delta a T^2 < \pi/2$

For $T = 1$ s, $\delta a < \sim 5 \cdot 10^{-8}$ m/s²

But, one can tolerate larger fluctuations provided they are slow,
since we can compensate for them and remain close to mid-fringe

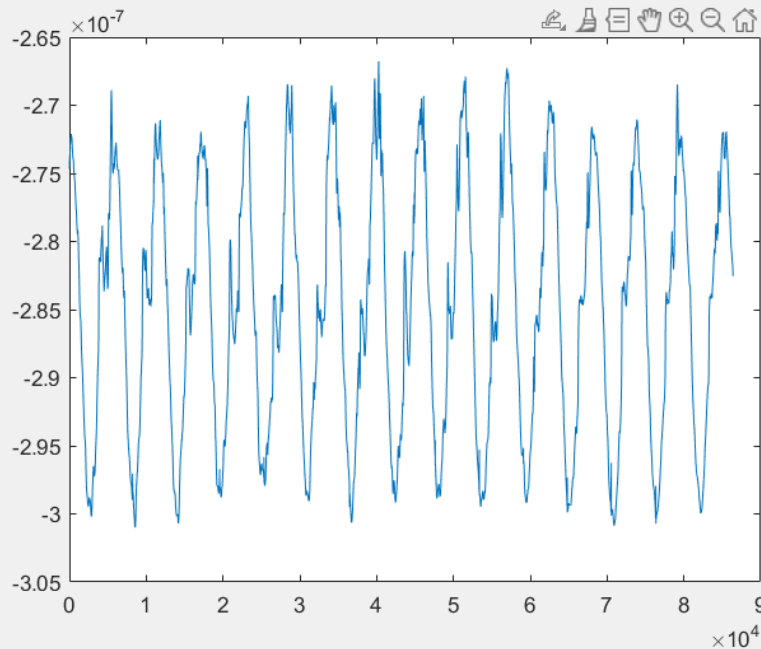
Showstopper : $k \delta a T^2 > \pi$, with δa the cycle to cycle variation



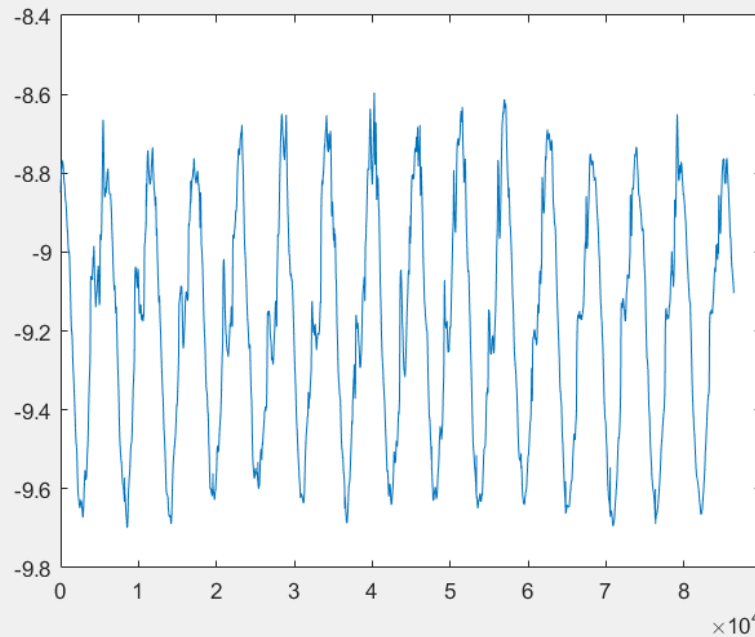
Impact of non-inertial accelerations

GRACE FON (1Hz data, 2019-01-01)

Acceleration a_x (m/s²)



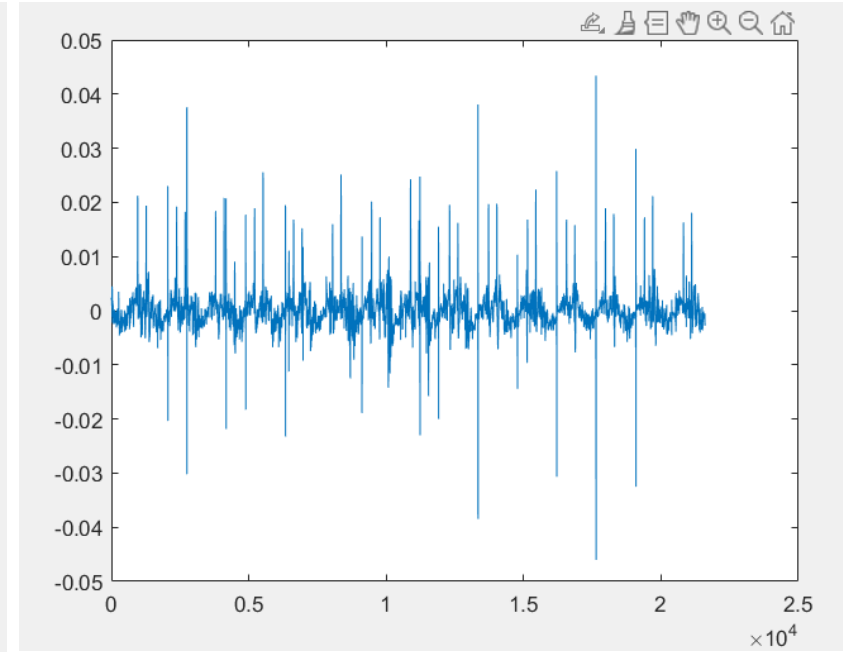
Phase (rad)



1 rad ptp, but slow fluctuations

Phase difference
between consecutive cycles (rad)

$2T = 2s$



Operation at 500 km altitude : $2T = 2s$ OK. Can be extended to $2T = 5-10 s$
But at 350 km, $2T$ limited to $< 2s$, except if hybridization with a classical sensor

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Development of the instrument simulator

LTE responsible for the development of a simulation tool for the generation of synthetic data

Inputs

- Source parameters (position, velocity, temperature, number of atoms ...), mean values and fluctuations
- Environmental conditions (non gravitational accelerations, satellite attitude ...)

Outputs

- Atomic populations, transition probability time series
- Corresponding accelerations

Used for validation of

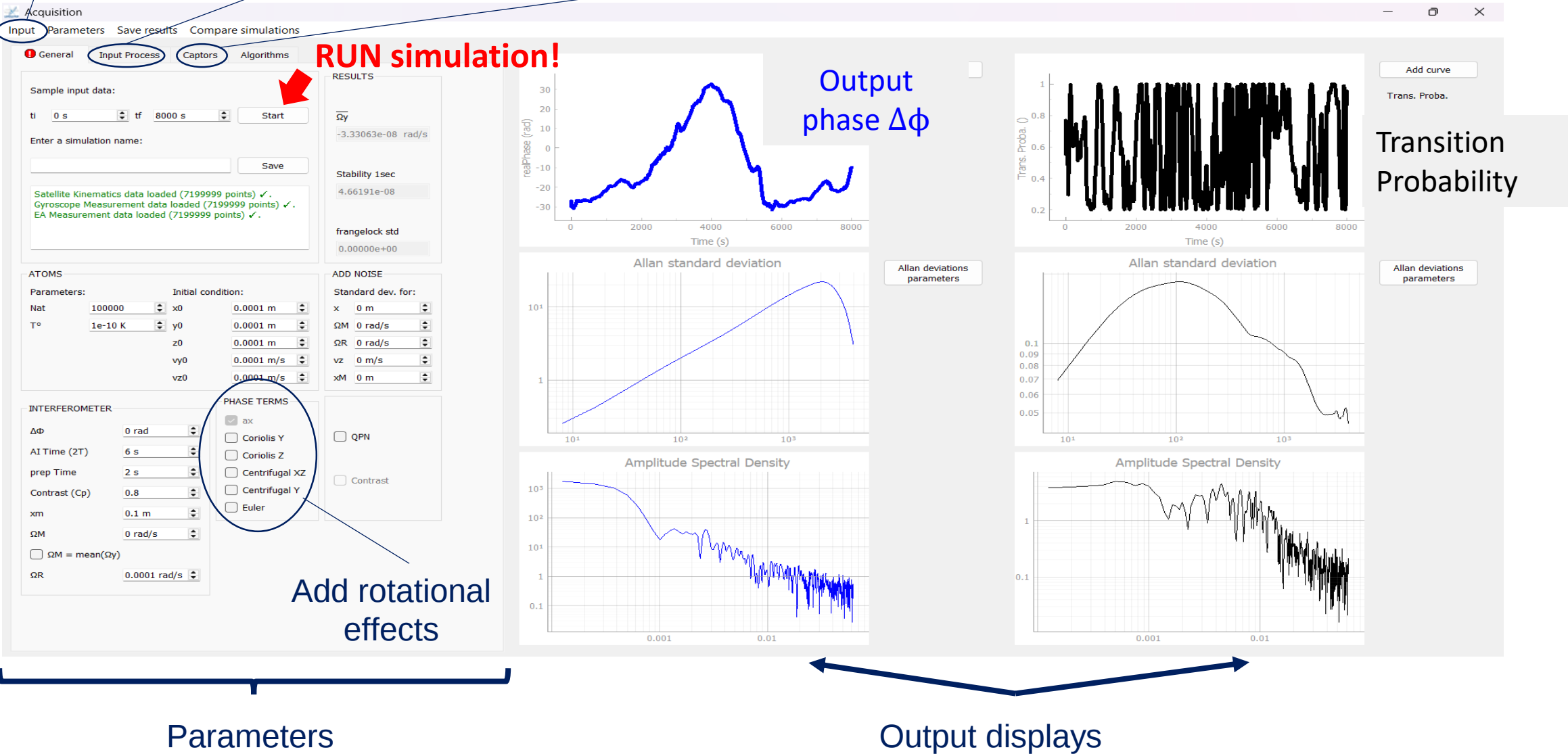
- Measurement methods
- Calibration phases (determination of drift velocities and positions wrt center of mass of the satellite)
- Hybridization protocols with classical sensors (bias determination ...)
- Gravity field recovery methods (in collaboration with geodesists)

Instrument simulator

Import acceleration data

Add noise to the input signals

Integrate other sensors (EA-ACC, Gyroscope)



Conclusion

Quantum accelerometry is a candidate technology for future accelerometers in space

Space geodesy could benefit from its improved measurement noise, in particular at low frequency

Strong push by the EC (+CNES/DLR) to make the first demonstration of a quantum accelerometer in orbit and to prepare future geodesy missions